A Framework for Scientific Workflow Reproducibility in the Cloud

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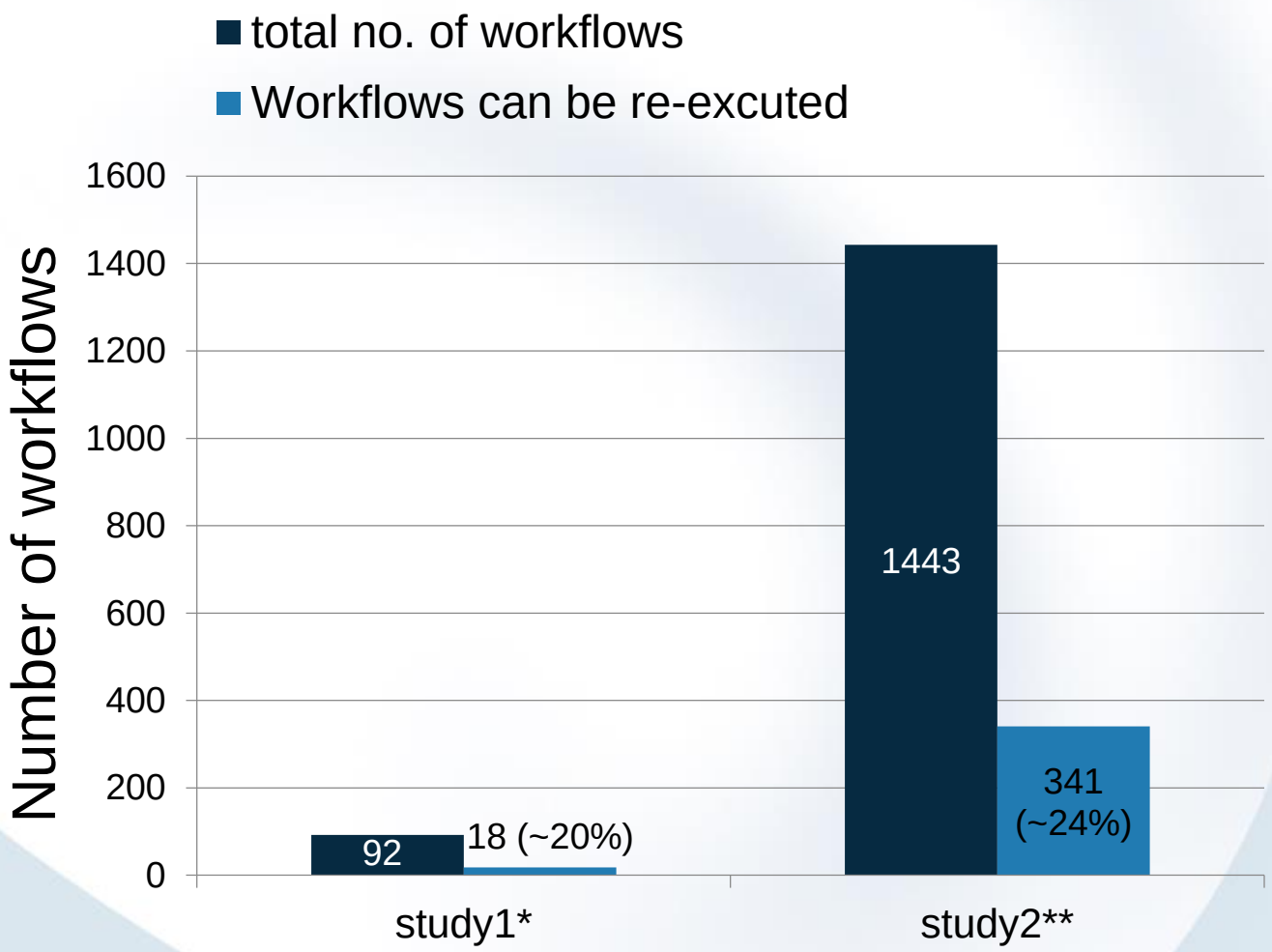
In this paper

- A new framework for repeatability and reproducibility of scientific workflow
- Integrating logical and physical preservation approaches
- Offering Workflow/tasks repositories with version control
- Supporting automatic deployment and image capture of workflows and tasks

Outline

- Background
- Challenges for workflow reproducibility
- Our solution for logical and physical preservations
- Overview of reproducibility framework
- Experiments and results
- Conclusions

Workflows & Reproducibility



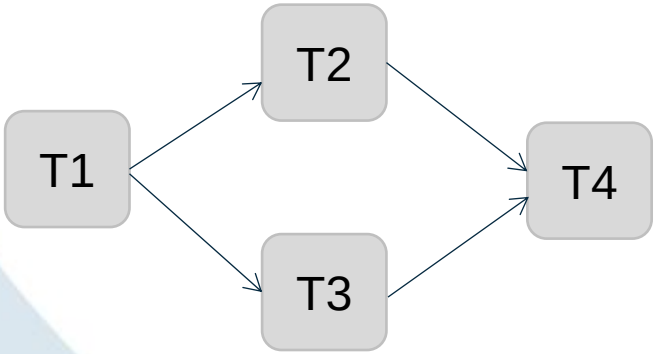
*Zhao et al, “Why workflows break Understanding and combating decay in Taverna workflows,” 2012

**Mayer et al, “A Quantitative Study on the Re-executability of Publicly Shared Scientific Workflows”, 2015

Challenges for workflow reproducibility

- Insufficiently detailed workflow description
- Insufficient description of the execution environment
- Unavailable execution environments
- Absence of & changes in the external dependencies
- Missing input data

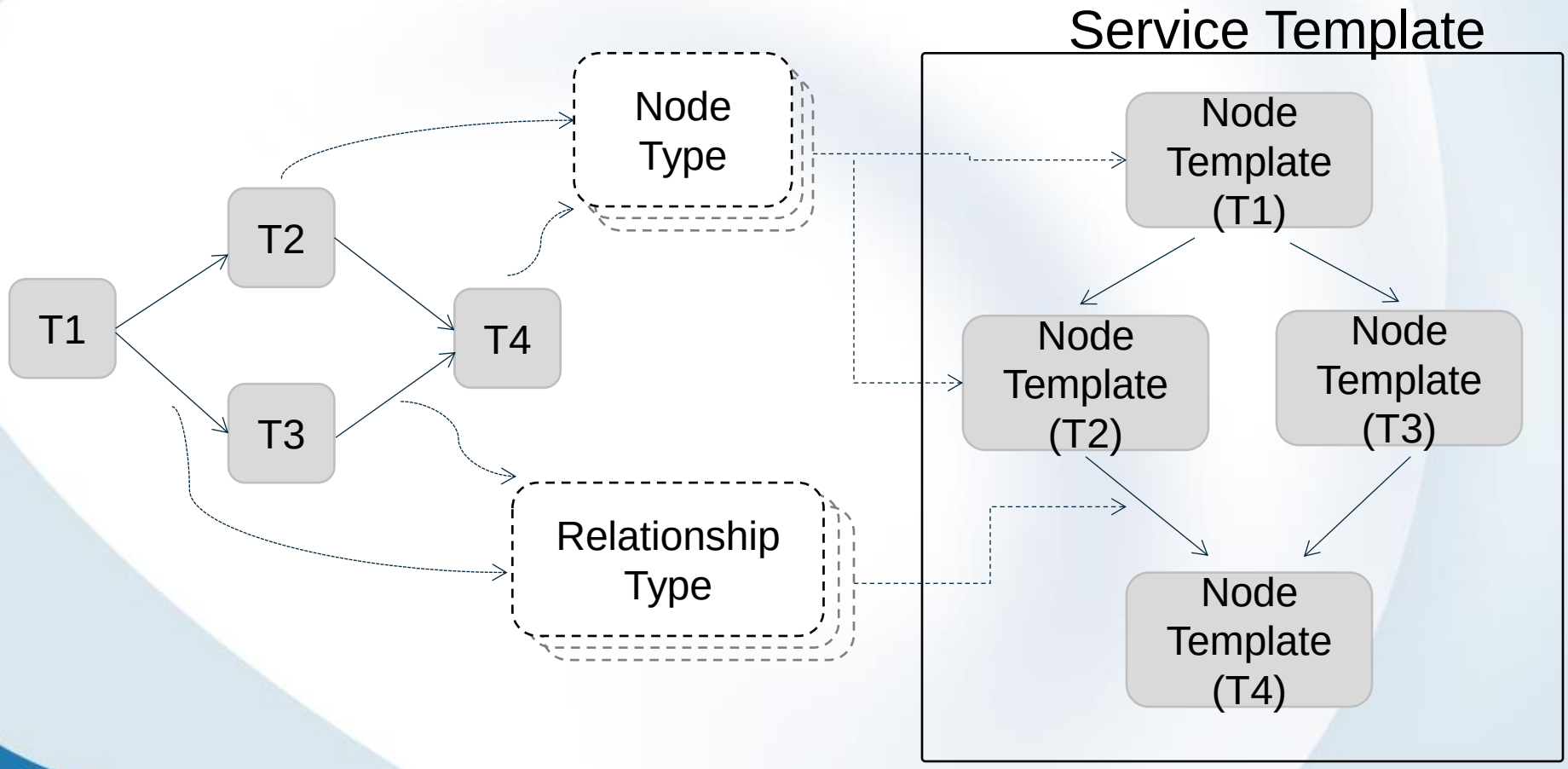
Common reproducibility approaches



Logical preservation

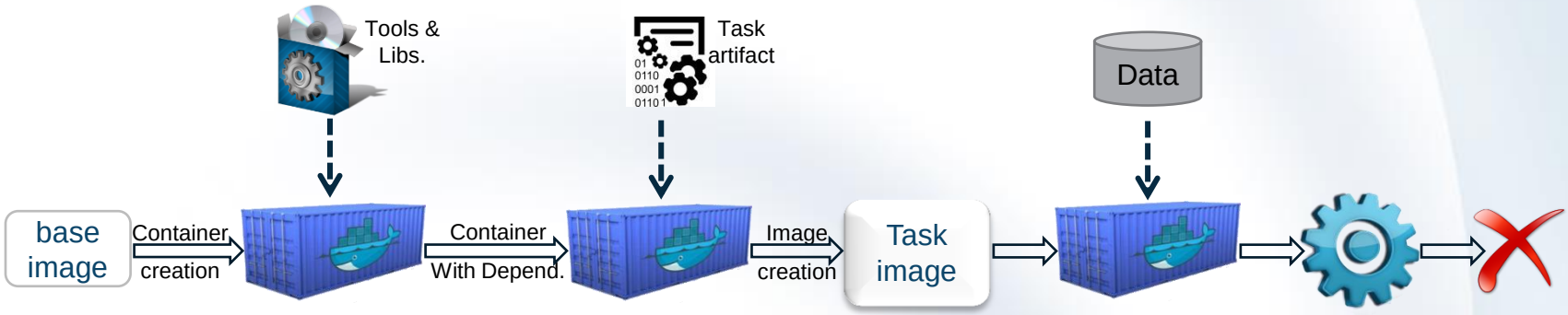
Physical preservation

Using TOSCA as a logical preservation

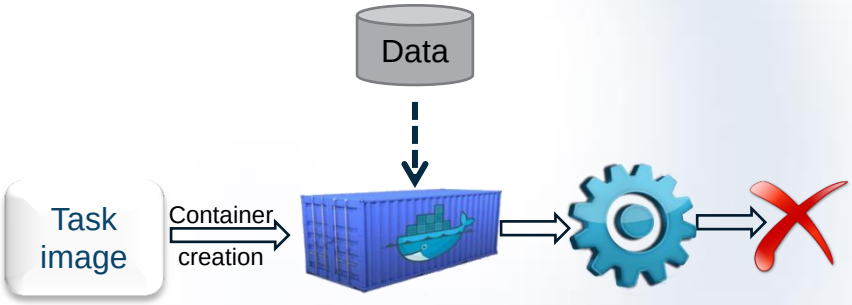


Workflow and execution environment description

Using Docker for physical preservation



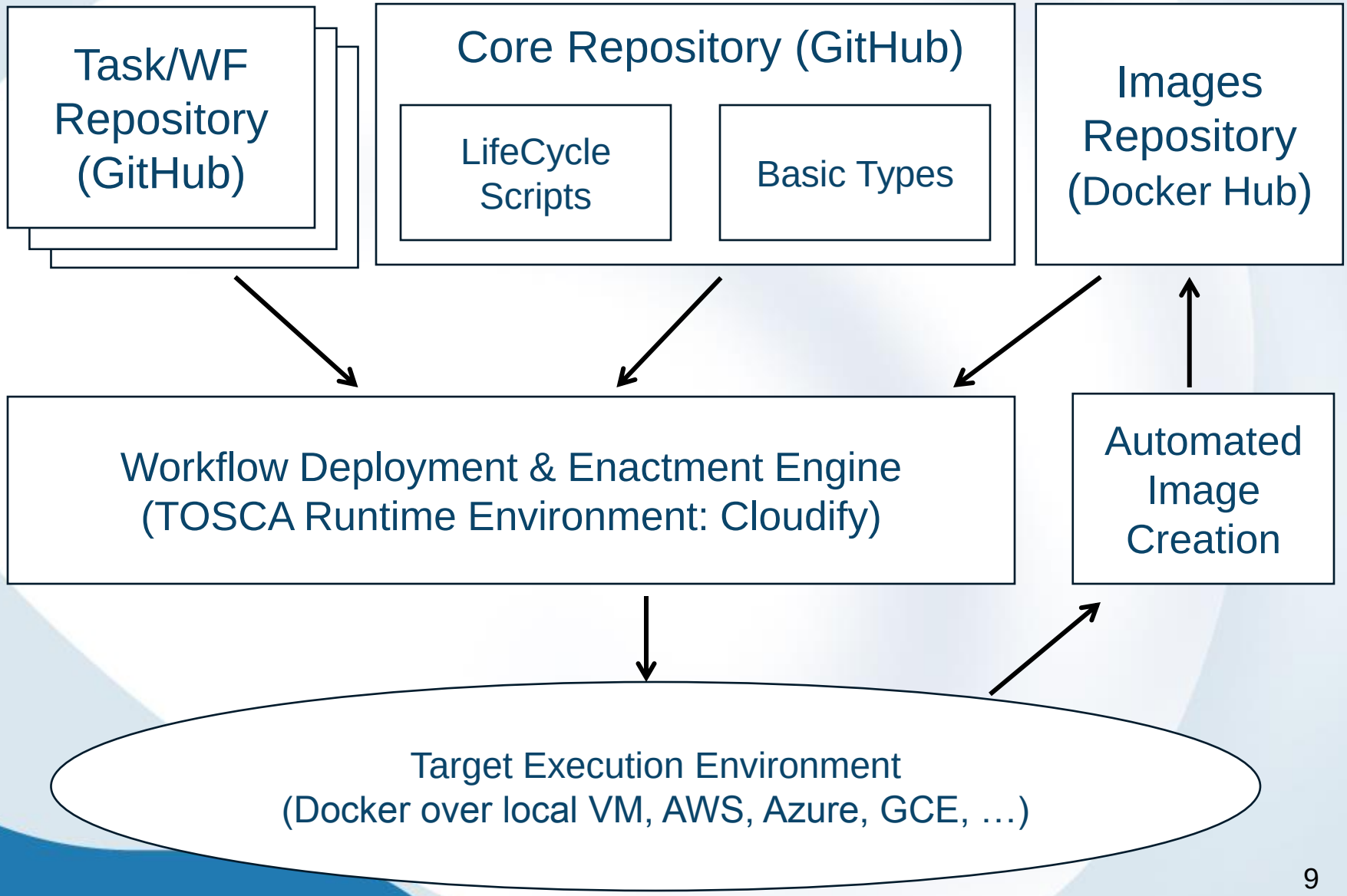
(a) Initial task deployment & execution



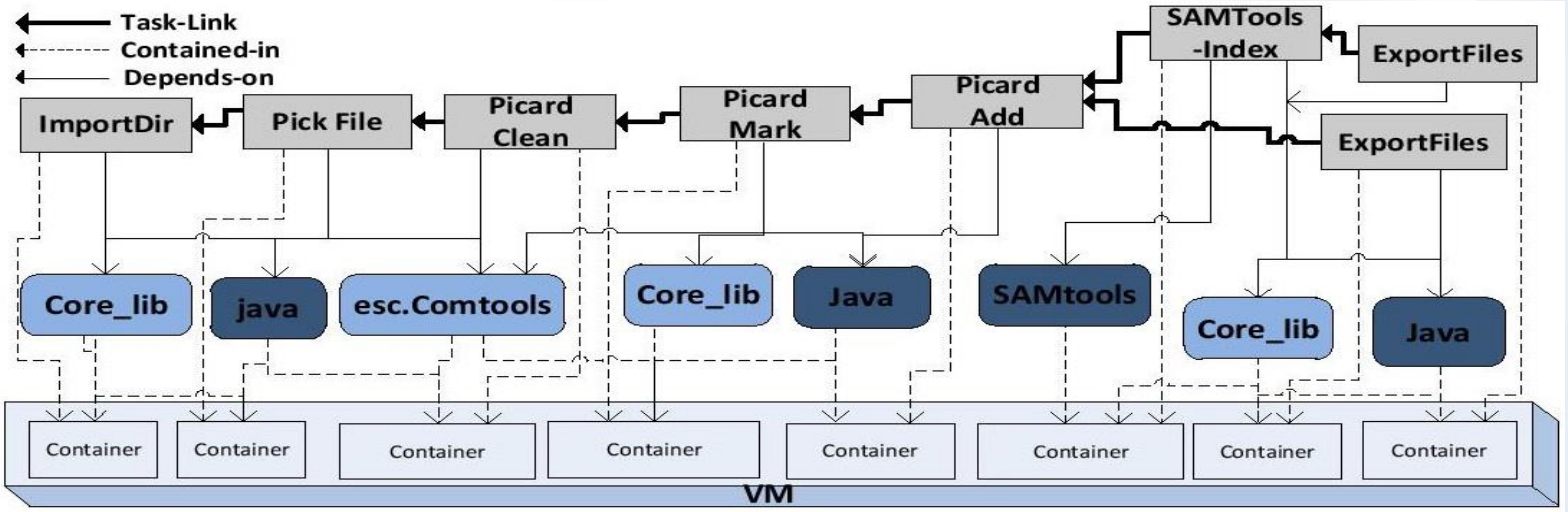
(b) Task deployment & execution with task image

Preserving execution environment and dependencies, tracking changes

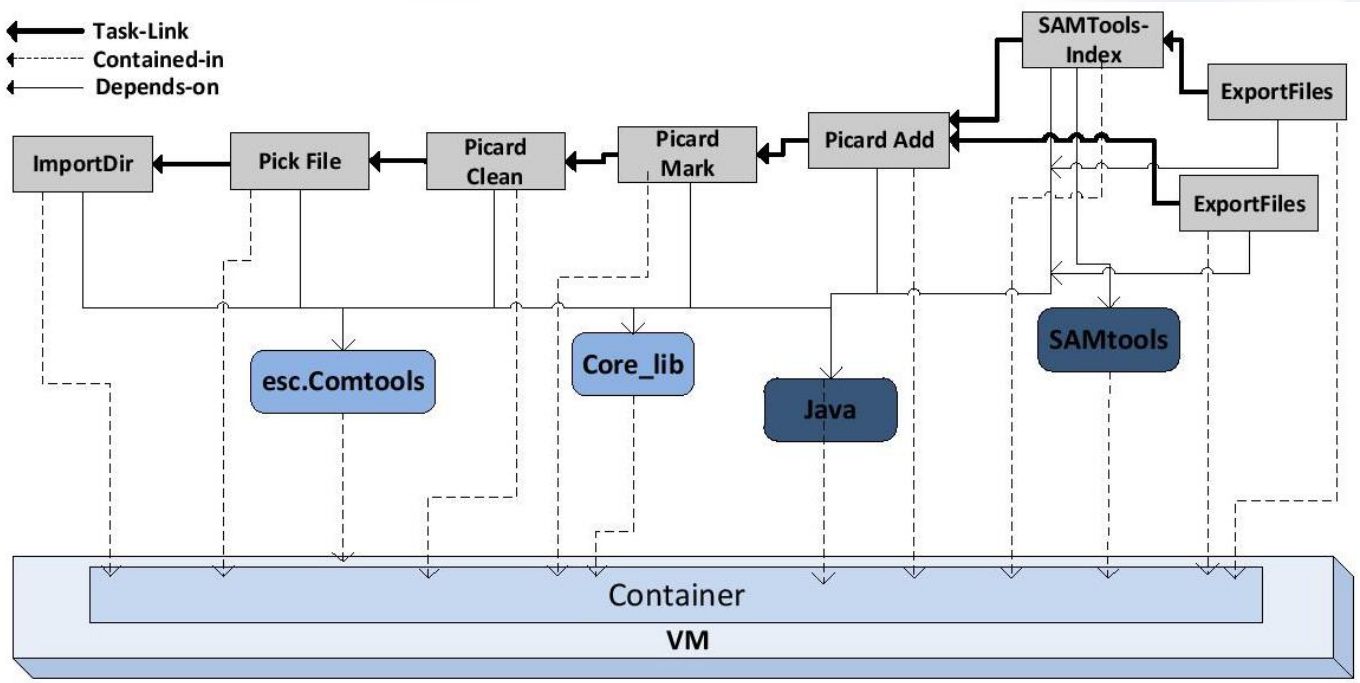
Reproducibility Framework

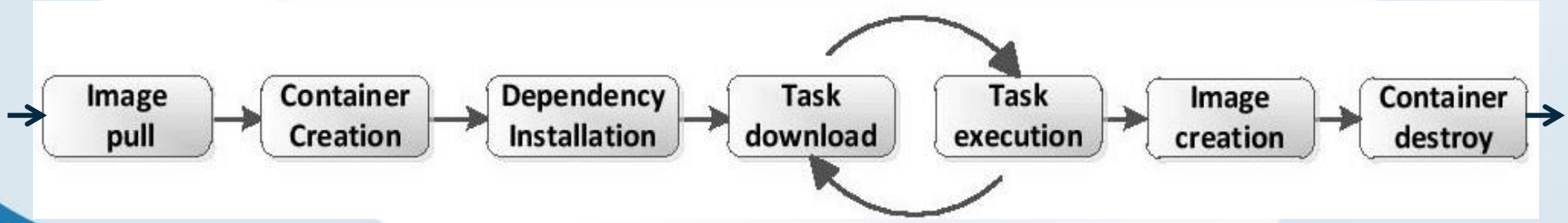


Multi-container deployment

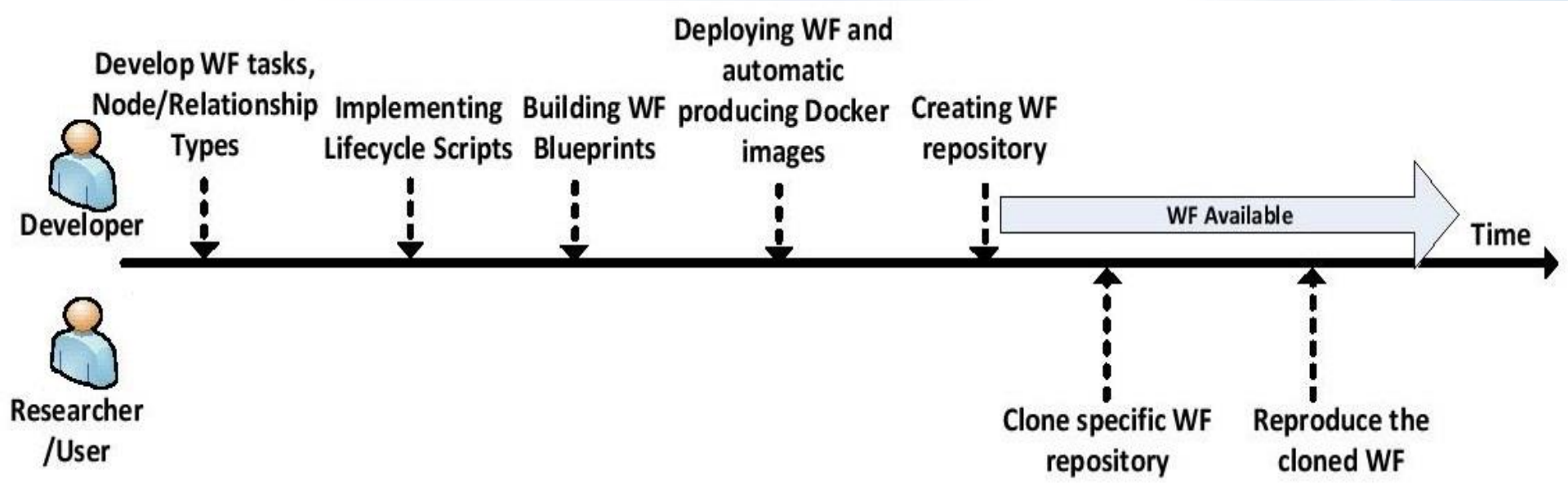


Single container deployment

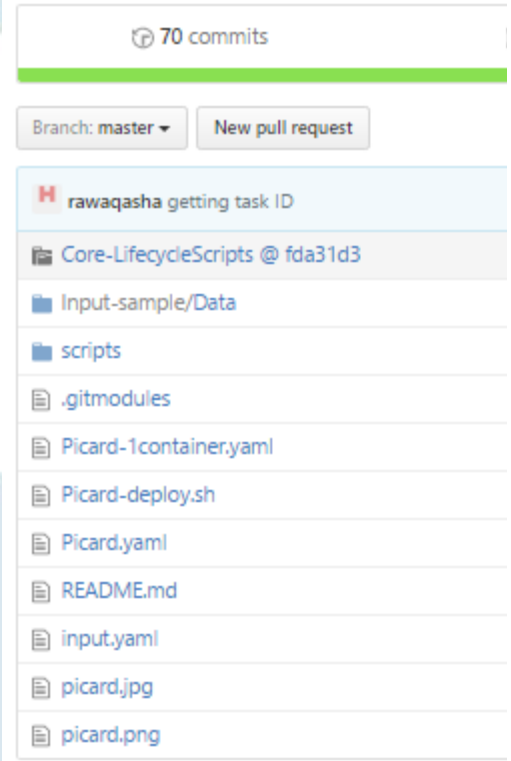




Time line of workflow devOps



Workflow repository



Outputs:

output-folder: '~/blueprint-name'
output-file(s): {index-BAI-files, output-SAM_BAM-files}
description:
types: {' ', ' '}

Execution-Environment:

Cloudify-version: 3.2
Docker-version: 1.8+
OS-type: ubuntu14.04
Disk-space: 10 GB
RAM: 3 GB

Deployment Instruction

This repository includes all files and scripts to deploy Picard workflow on Multiple Docker containers as follow:

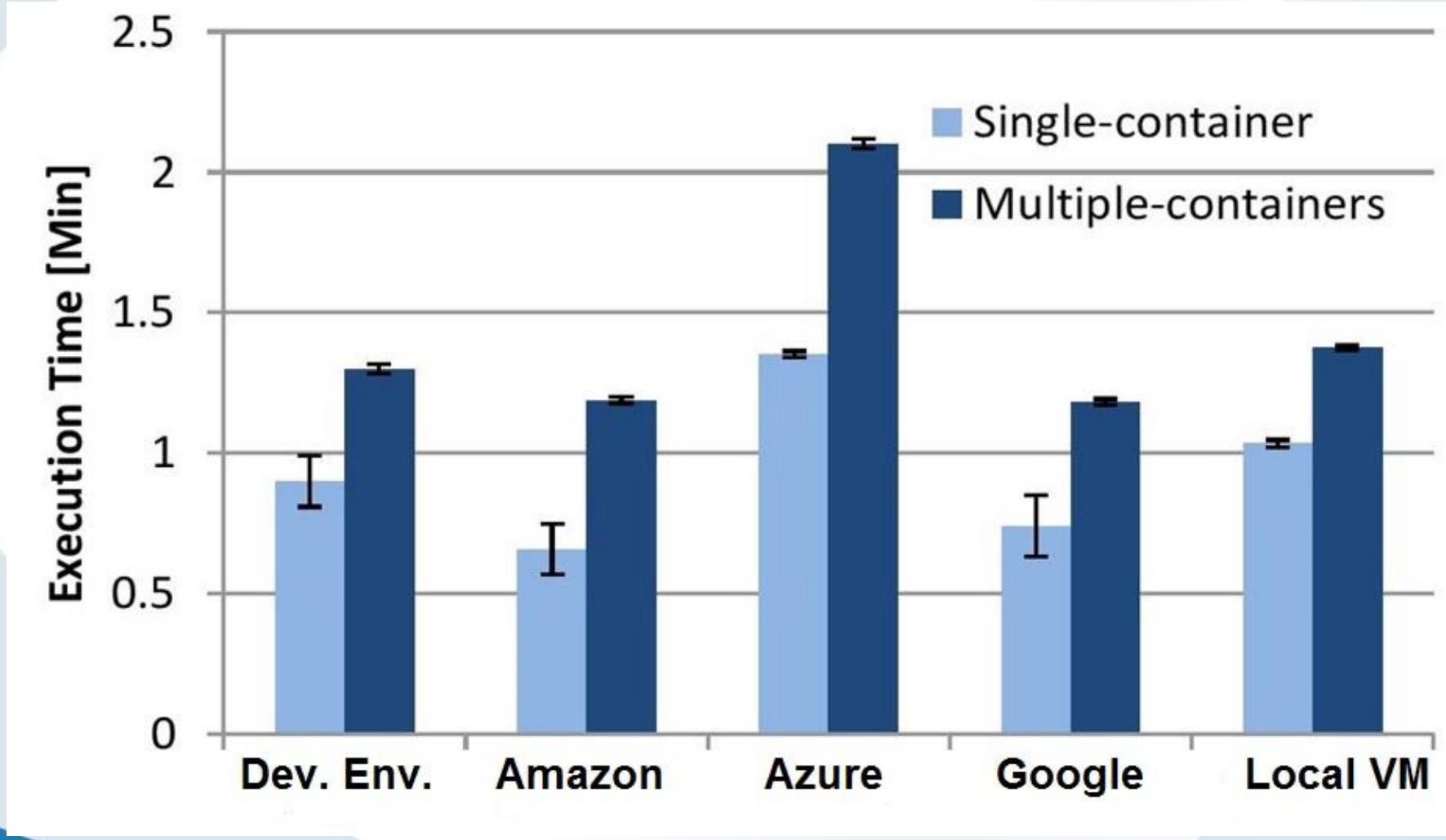
1- Clone the repository to your machine, open a terminal window and change to workflow repository.
2- To execute the workflow with multi containers and the attached input sample, in the terminal run:
. ./Picard-deploy.sh 1
3- If you have own input files, copy your files Dir to Picard/Input-sample folder, open Input.yaml file and change input Dir name, then
run: . ./Picard-deploy.sh 1

4- To execute the workflow with single container, follow either step 2 or 3 but run:
. ./Picard-deploy 2

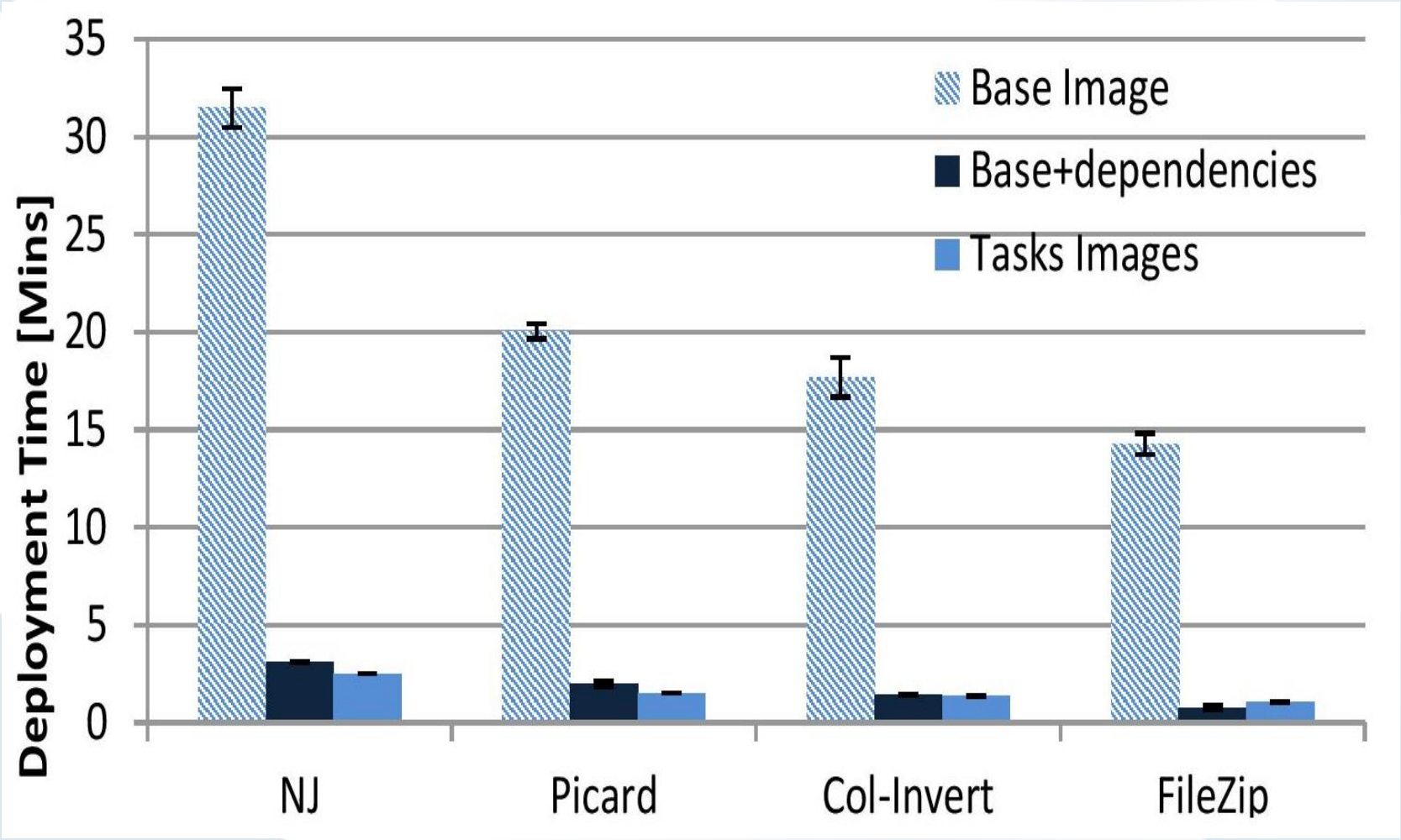
Preserving description, input data, tracking changes and deployment instructions

Experiments and Results

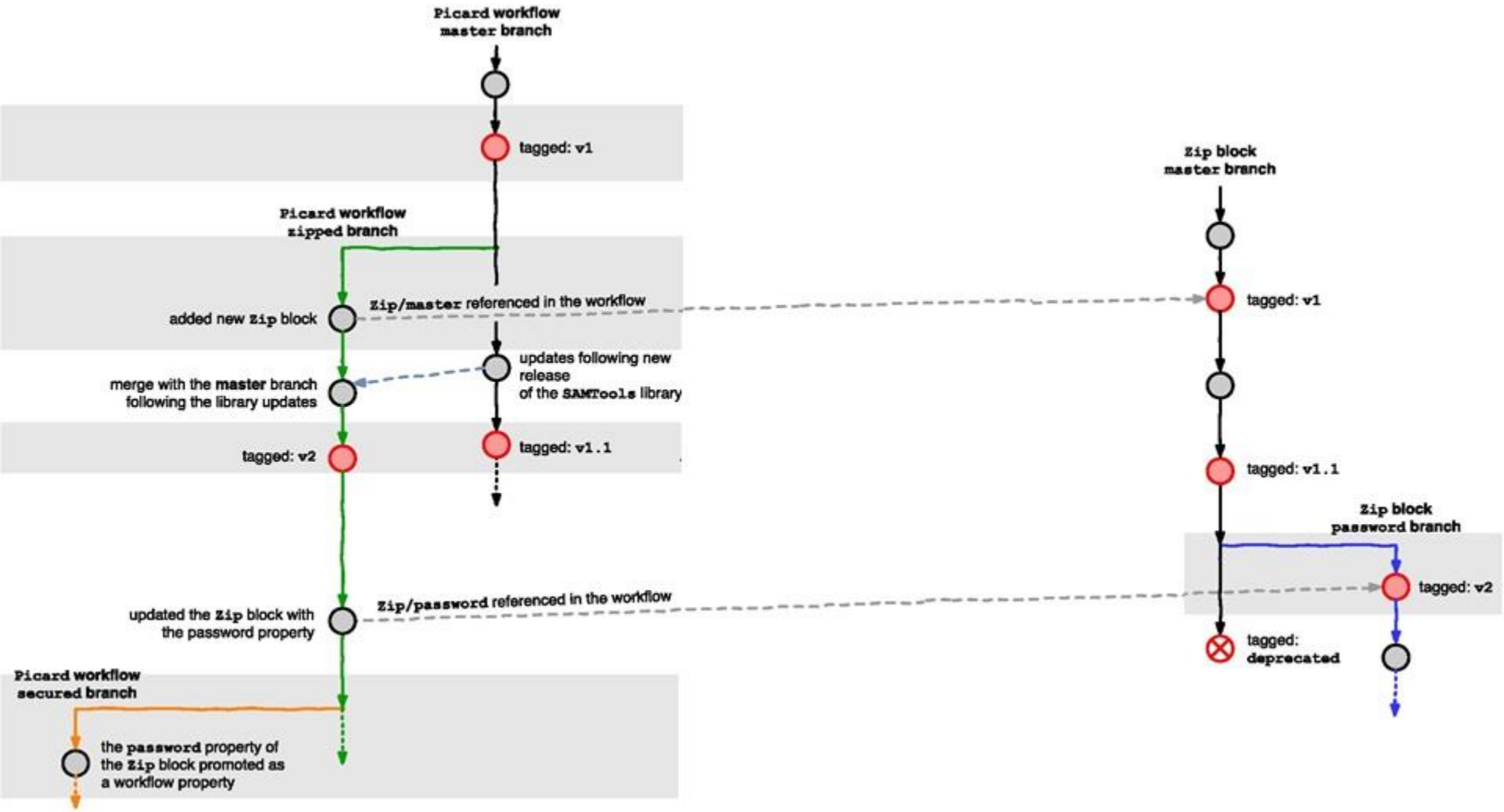
1- Repeatability of a workflow on different clouds



2- Automatic image capture for improved performance



3- Reproducibility in the face of development changes



Conclusions

- Full workflow reproducibility is a long-standing issue
- TOSCA description is used for logical preservation
- Docker images for tasks/workflows support physical preservation
- Changes tracking and automatic deployment also contribute to a comprehensive solution of the problem
- Integration of these techniques addresses majority of the issues related to workflow decay

THANK YOU